



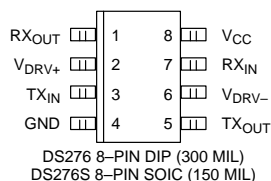
DS276

Low Power Transceiver Chip

FEATURES

- Low-power serial transmitter/receiver for battery-backed systems
- Transmitter steals power from receive signal line to save power
- Single 3V or 5V operation
- Full duplex operation up to 20K bps
- Ultra-low static current
- Compatible with RS-232-E signals

PIN ASSIGNMENT



PIN DESCRIPTION

RX _{OUT}	RS-232 Receiver Output
V _{DRV+}	Transmit Driver Positive Supply
TX _{IN}	RS-232 Driver Input
GND	System Ground (0V)
TX _{OUT}	RS-232 Driver Output
V _{DRV-}	Transmit Driver Negative Supply
RX _{IN}	RS-232 Receiver Input
V _{CC}	System Logic Supply (3–5V)

ORDERING INFORMATION

DS276	8-Pin DIP
DS276S	8-Pin SOIC

DESCRIPTION

The DS276 Line-Powered RS-232 Transceiver Chip is a CMOS device that provides a low-cost, very low-power interface to RS-232 serial ports. The receiver input translates RS-232 signal levels to common CMOS/TTL levels. The transmitter can be used with independently supplied positive and negative supplies, but in most cases will be used with the positive supply sharing the logic supply and the negative supply stolen from the receive RS-232 signal when that signal is in a negative state (marking). By using an external reservoir capacitor and Schottky diode (see Figure 4) this nega-

tive supply can be maintained even during full-duplex operation. Since most serial communication ports remain in a negative state statically, using the receive signal for negative power greatly reduces the DS276's static power consumption. This feature is especially important for battery-powered systems such as laptop computers, remote sensors, and portable medical instruments. During an actual communication session, the DS276's transmitter will use system power (3–12 volts) for positive transitions while still employing the receive signal for negative transitions.

OPERATION

Designed for the unique requirements of battery-backed systems, the DS276 provides a low-power full- or half-duplex interface to an RS-232 serial port. Typically, a designer must use an RS-232 device which uses system power during both negative and positive transitions of the transmit signal to the RS-232 port. If the connector to the RS-232 port is left connected for an appreciable time after the communication session has ended, power will statically flow into that port, draining the battery capacity. The DS276 eliminates this static current drain by stealing current from the receive line (RX_{IN}) of the RS-232 port when that line is at a negative level (marking). Since most asynchronous communication over an RS-232 connection typically remains in a marking state when data is not being sent, the DS276 will not consume system power in this condition. System power would only be used when positive-going transitions are needed on the transmit RS-232 output (TX_{OUT}) when data is sent. However, since synchronous communication sessions typically exhibit a very low duty-cycle, overall system power consumption remains low.

RECEIVER SECTION

The RX_{IN} pin is the receive input for an RS-232 signal whose levels can range from ± 3 to ± 15 volts. A negative data signal is called a mark while a positive data signal is called a space. These signals are inverted and then level-shifted to normal +3 or +5 volt CMOS/TTL logic levels. The logic output associated with RX_{IN} is RX_{OUT} which swings from V_{CC} to ground. Therefore, a mark on RX_{IN} produces a logic 1 at RX_{OUT} ; a space produces a logic 0.

The input threshold of RX_{IN} is typically around 1.8 volts with 500 millivolts of hysteresis to improve noise rejection. Therefore, an input positive-going signal must exceed 1.8 volts to cause RX_{OUT} to switch states. A negative-going signal must now be lower than 1.3 volts (typically) to cause RX_{OUT} to switch again. An open on RX_{IN} is interpreted as a mark, producing a logic 1 at RX_{OUT} .

TRANSMITTER SECTION

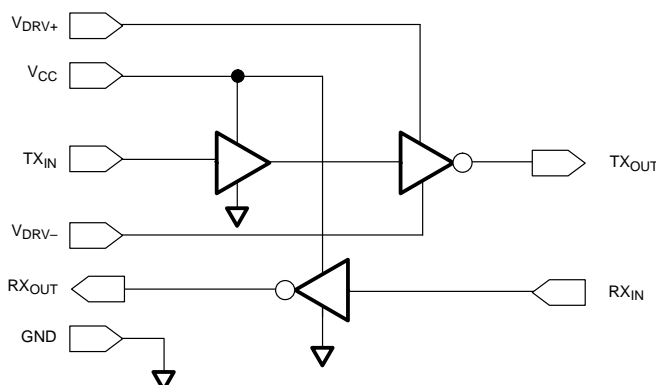
TX_{IN} is the CMOS/TTL-compatible input for data from the user system. A logic "1" at TX_{IN} produces a mark

(negative data signal) at TX_{OUT} while a logic 0 produces a space (positive data signal). As mentioned earlier, the transmitter section employs a unique driver design that can use the RX_{IN} line for swinging to negative levels. RX_{IN} can be connected via external circuitry to V_{DRV-} to allow stored charge to supply this voltage during marking (or idle) states. When TX_{OUT} needs to transition to a positive level, it uses the V_{DRV+} power pin for this level. V_{DRV+} can be a voltage supply between 3 to 12 volts, and in many situations it can be tied directly to the V_{CC} supply. It is important to note that V_{DRV+} must be greater than or equal to V_{CC} at all times.

The voltage range on V_{DRV+} permits the use of a 9V battery in order to provide a higher voltage level when TX_{OUT} is in a space state. When V_{CC} is shut off to the DS276 and V_{DRV+} is still powered (as might happen in a battery-backed condition), only a small leakage current (about 50–100 nA) will be drawn. If TX_{OUT} is loaded during such a condition, V_{DRV+} will draw current only if RX_{IN} is not in a negative state. During normal operation ($V_{CC} = 3$ or 5 volts), V_{DRV+} will draw less than 2 μA when TX_{OUT} is marking. Of course, when TX_{OUT} is spacing, V_{DRV+} will draw substantially more current—about 3 mA depending upon its voltage and the impedance that TX_{OUT} sees. The TX_{OUT} output is slew-rate limited to less than 30 volts/us in accordance with RS-232 specifications. In the event TX_{OUT} should be inadvertently shorted to ground, internal current-limiting circuitry prevents damage, even if continuously shorted.

RS-232 COMPATIBILITY

The intent of the DS276 is not so much to meet all the requirements of the RS-232 specification as to offer a low-power solution that will work with most RS-232 ports with a connector length of less than 10 feet. As a prime example, the DS276 will not meet the RS-232 requirement that the signal levels be at least ± 5 volts minimum when terminated by a 3K Ω load and $V_{DRV+} = +3$ –5 volts. Typically 2.5 to 4 volts will be present at TX_{OUT} when spacing under this condition, depending on the supply voltage. However, since most RS-232 receivers will correctly interpret any voltage over 2 volts as a space, there will be no problem transmitting data.

DS276 BLOCK DIAGRAM Figure 1

APPLICATIONS INFORMATION

The DS276 is designed as a low-cost, RS-232-E interface expressly tailored for the unique requirements of battery-operated handheld products. As shown in the electrical specifications, the DS276 draws exceptionally low operating and static current. During normal operation when data from the handheld system is sent from the TX_{OUT} output, the DS276 only draws significant V_{DRV+} current when TX_{OUT} transitions positively (spacing). This current flows primarily into the RS-232 receiver's 3–7K Ω load at the other end of the attaching cable. When TX_{OUT} is marking (a negative data signal), the V_{DRV+} current falls dramatically since the negative voltage is provided by the transmit signal from the other end of the cable. This represents a large reduction in overall operating current, since typical RS-232 interface chips use charge-pump circuits to establish both positive and negative levels at the transmit driver output. To obtain the lowest power consumption from the DS276, observe the following guidelines: First, to minimize V_{DRV+} current when connected to an RS-232 port, always maintain TX_{IN} at a logic 1 when data is not being transmitted (idle state). This will force TX_{OUT} into the marking state, minimizing V_{DRV+} current. Second, V_{DRV+} current will drop significantly when V_{CC} is grounded. Therefore, if V_{DRV+} is derived independently from V_{CC} (for example connected to a 9V battery), the logic supply voltage can be turned off to achieve the lowest possible power state.

FULL-DUPLEX OPERATION

The DS276 is intended for full-duplex operation using the full-duplex circuit shown in Figure 4 to generate a negative rail from RX_{IN}. The 22 μ F capacitor forms a negative-charge reservoir; consequently, when the

TXD line RX_{IN} is spacing (positive), TX_{OUT} still has a negative source available for a time period determined by the capacitor and the load resistance at the other end (3–7K Ω).

SUPPLY VOLTAGE OPTIONS

The DS276 is intended primarily for use in single supply 3- or 5-volts systems. However several supply configurations are possible.

3V OPERATION

The simplest configuration is to use a single 3V supply for V_{CC} and V_{drv+} , and connect V_{drv-} to ground. This will result in the lowest power consumption and will give adequate serial communication between two similar devices over short distances, and into larger loads than the 3K Ω RS-232 standard (Figure 2).

If V_{drv+} is increased to 5V, and V_{drv-} decreased (to less than -2V) communication with standard RS-232 devices is possible, although of course the output voltage swing of the DS276 remains below the RS-232 specification. The V_{drv-} supply can be derived using the "stealing" technique shown in Figure 4.

5V OPERATION

The use of a single 5V supply for V_{CC} and V_{drv+} , and V_{drv-} derived using the circuit in Figure 4 can produce reliable communication with standard RS-232 devices, although the DS276 output voltage swings are below the RS-232 minimum (Figure 3).

Increasing the magnitude of the voltage to V_{drv+} to 10 volts or more will result in "true" RS-232 output voltage levels.

ABSOLUTE MAXIMUM RATINGS*

V_{CC}	–0.3V to +7.0V
V_{DR+}	–0.3V to +13V
V_{DR-}	–13V to +0.3V
RX_{IN}	–15V to +15V
TX_{IN}	–0.3V to $V_{CC}+0.3V$
TX_{OUT}	–15V to +15V
RX_{OUT}	–0.3V to $V_{CC}+0.3V$
Operating Temperature	0°C to 70°C
Storage Temperature	–55°C to +125°C
Soldering Temperature	260°C for 10 seconds

* This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operation sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods of time may affect reliability.

RECOMMENDED DC OPERATING CONDITIONS(t_A = 0°C to 70°C)

PARAMETER	SYMBOL	CONDITION	MIN	TYP	MAX	UNITS	NOTES
Logic Supply Voltage	V_{CC}		2.7	3–5	5.5	V	1
Transmit Driver Supply	V_{DR+} V_{DR+}	$V_{CC}=5V\pm10\%$ $V_{CC}=2.7-3.6V$	V_{CC} V_{CC}	5–12 3–5	13 5.5	V V	1 1
Transmit Driver Supply	V_{DR-}		–15		0	V	1
High-level Input Voltage	V_{IH}		2		$V_{CC} + 0.3$	V	
Low-level Input Voltage	V_{IL}		–0.3		0.8	V	
RX_{IN} Input Voltage	V_{RS}		–15		+15	V	1

ELECTRICAL CHARACTERISTICS–3V OPERATION(t_A = 0°C to 70°C)

PARAMETER	SYMBOL		MIN	TYP	MAX	UNITS	NOTES
Logic Supply Voltage	V_{CC}		2.7		3.6	V	
Dynamic Supply Current	I_{DRV1} I_{CC1} I_{DRV1} I_{CC1}	$TX_{IN} = V_{CC}$ $TX_{IN} = V_{CC}$ $TX_{IN} = GND$ $TX_{IN} = GND$		400 40 3.8 40	800 100 5 100	uA uA mA uA	2 2 2 2
Static Supply Current	I_{DRV2} I_{CC2} I_{DRV2} I_{CC2}	$TX_{IN} = V_{CC}$ $TX_{IN} = V_{CC}$ $TX_{IN} = GND$ $TX_{IN} = GND$		1.5 10 3.8 10	10 15 5 20	uA uA mA uA	3 3 3 3
Driver Leakage Current	I_{DRV3}	$V_{CC} = 0$		0.05	1	uA	4
TX_{OUT} Level High	V_{OTXH}	$V_{DRV+}=V_{CC}=2.7V$ $V_{DRV-}=0$	2	2.4		V	5
		$V_{DRV+}=4.5V$, $V_{DRV-}=-12V$	3.8	4		V	6

ELECTRICAL CHARACTERISTICS—3V OPERATION cont'd(t_A = 0°C to 70°C)

PARAMETER	SYMBOL		MIN	TYP	MAX	UNITS	NOTES
TX _{OUT} Level Low	V _{OTXL}	V _{DRV+} = V _{CC} = 2.7V V _{DRV-} = 0		0.2	0.3	V	5
		V _{DRV+} = V _{CC} to 5.5V V _{DRV-} = -12V		-11	-10	V	6
TX _{OUT} Short Circuit Current	I _{SC}	V _{DRV+} = 5.5V, V _{DRV-} = -12V			85	mA	7
TX _{OUT} Output Slew Rate	t _{SR}				30	V/us	
Propagation Delay	t _{PD}			5		us	8
RX _{IN} Input Threshold Low	V _{TL}		0.8	1.0	1.6	V	
RX _{IN} Input Threshold High	V _{TH}		1.2	2.0	2.4	V	
RX _{IN} Threshold Hysteresis	V _{HYS}		0.4	1.0		V	9
RX _{OUT} Output Current High	I _{OH}	V _{CC} = 2.7V V _{OH} = 2V			-0.5	mA	
RX _{OUT} Output Current Low	I _{OL}	V _{CC} = 2.7V V _{OL} = 0.4V	0.5			mA	

NOTES:

1. V_{DRV+} must be greater than or equal to V_{CC}, RX_{IN} must be greater than V_{DRV-}.
2. See test circuit in Figure 5.
3. See test circuit in Figure 6.
4. See test circuit in Figure 7.
5. R_L = 3KΩ to ground. Max data rate = 20K bps.
6. R_L = 3KΩ to ground. Max data rate = 50K bps.
7. TX_{IN} = V_{IL}.
8. See test circuit in Figure 8.
9. V_{HYS} = V_{TH} - V_{TL}.

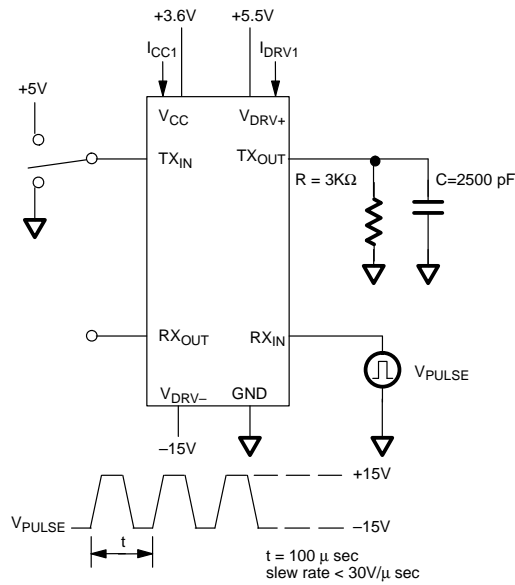
+ELECTRICAL CHARACTERISTICS—5V OPERATION(t_A = 0°C to 70°C)

PARAMETER	SYMBOL	CONDITION	MIN	TYP	MAX	UNITS	NOTES
Logic Supply Voltage	V _{CC}		4.5	5	5.5	V	
Dynamic Supply Current	I _{DRV1}	TX _{IN} = V _{CC}		400	800	uA	1
	I _{CC1}	TX _{IN} = V _{CC}		40	100	uA	1
	I _{DRV1}	TX _{IN} = GND		3.8	5	mA	1
	I _{CC1}	TX _{IN} = GND		40	100	uA	1
Static Supply Current	I _{DRV2}	TX _{IN} = V _{CC}		1.5	10	uA	2
	I _{CC2}	TX _{IN} = V _{CC}		10	15	uA	2
	I _{DRV2}	TX _{IN} = GND		3.8	5	mA	2
	I _{CC2}	TX _{IN} = GND		10	20	uA	2
Driver Leakage Current	I _{DRV3}	V _{CC} = 0		0.05	1	uA	3
TX _{OUT} Level High	V _{OTXH}	V _{DRV+} =V _{CC} = 4.5V V _{DRV-} =0	3.3	3.8		V	4
		V _{DRV+} =12V, V _{DRV-} =0 to -12V	10	11		V	5
TX _{OUT} Level Low	V _{OTXL}	V _{DRV+} =V _{CC} to 12V, V _{DRV-} =-12V		-11	-10	V	4
		V _{DRV+} =V _{CC} V _{DRV-} =0		0.2	0.3	V	5
TX _{OUT} Short Circuit Current	I _{SC}	V _{DRV+} =12V, V _{DRV-} =-12V			85	mA	6
TX _{OUT} Output Slew Rate	t _{SR}				30	V/us	
Propagation Delay	t _{PD}			5		us	7
RX _{IN} Input Threshold Low	V _{TL}		0.8	1.2	6	V	
RX _{IN} Input Threshold High	V _{TH}		1.6	2	2	V	
RX _{IN} Threshold Hysteresis	V _{HYS}		0.5	0.8		V	8
RX _{OUT} Output Current High	I _{OH}	V _{CC} =4.5V, V _{OH} =2.4V			-1	mA	
RX _{OUT} Output Current Low	I _{OL}	V _{CC} =4.5V, V _{OL} =0.4V	3			mA	

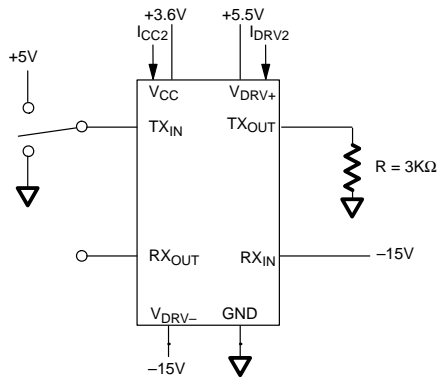
NOTES:

1. See test circuit in Figure 9.
2. See test circuit in Figure 10.
3. See test circuit in Figure 11.
4. R_L = 3KΩ to ground. Max data rate = 20K bps.
5. R_L = 3KΩ to ground. Max data rate = 100K bps.
6. TX_{IN} = V_{IL}.
7. See test circuit in Figure 12.
8. V_{HYS} = V_{TH} - V_{TL}.

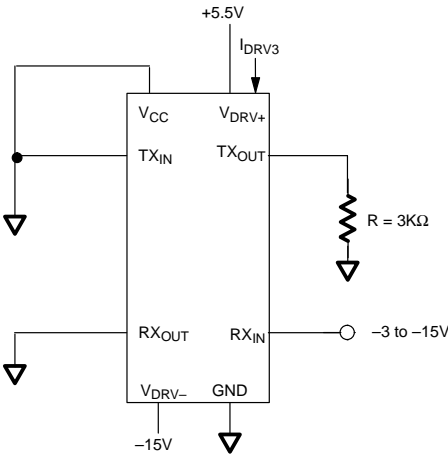
DYNAMIC OPERATING CURRENT TEST CIRCUIT Figure 5



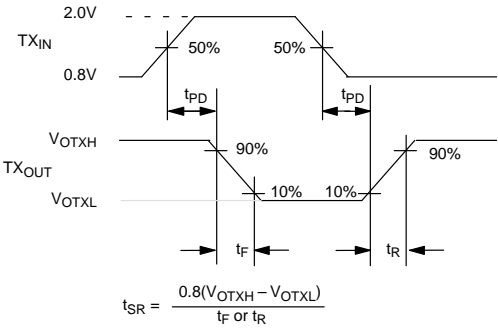
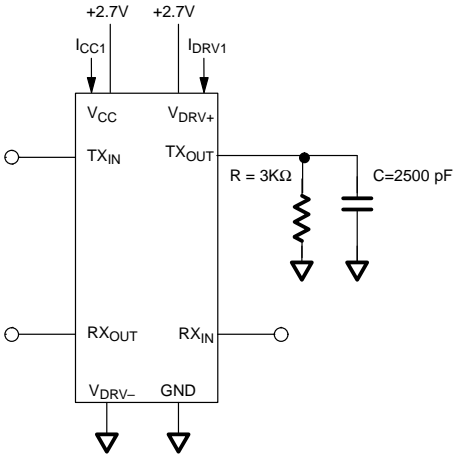
STATIC OPERATING CURRENT TEST CIRCUIT Figure 6



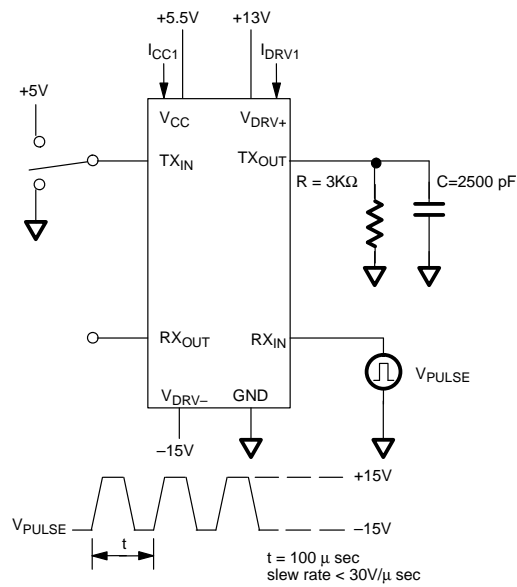
DRIVER LEAKAGE TEST CIRCUIT Figure 7



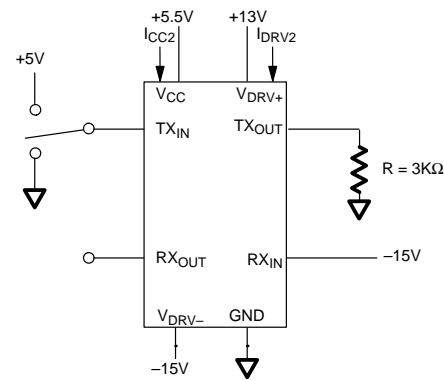
PROPAGATION DELAY TEST CIRCUIT Figure 8



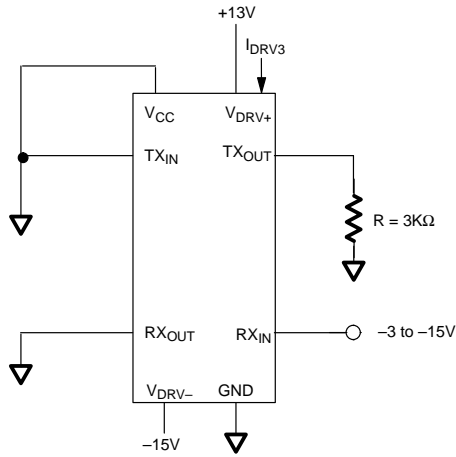
DYNAMIC OPERATING CURRENT TEST CIRCUIT Figure 9



STATIC OPERATING CURRENT TEST CIRCUIT Figure 10



DRIVER LEAKAGE TEST CIRCUIT Figure 11



PROPAGATION DELAY TEST CIRCUIT Figure 12

